### Hybridizing Biology and Robotics through Integration for Deployable Systems (HyBRIDS) Webinar

Samantha Peters DARPA Innovation Fellow Max Olender DARPA Innovation Fellow

Advanced Research Concepts (ARC) Opportunity Overview DARPA-EA-25-02-02

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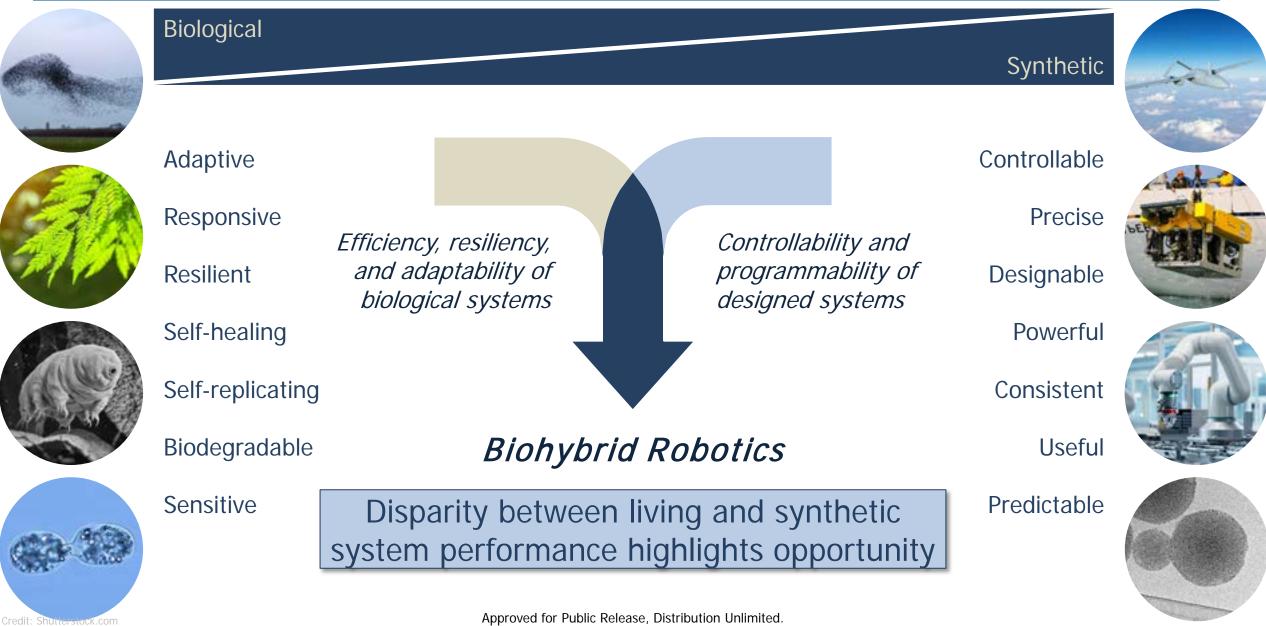
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# Biohybrid Robotics Merges Benefits of Biological and Synthetic Systems





# BiomimeticImitating natural biological designs orprocesses in engineering or invention

# BioinspiredInspired by or based on biologicalstructures or processes

Biohybrid

<u>Containing</u> or composed of both biological and non-biological components



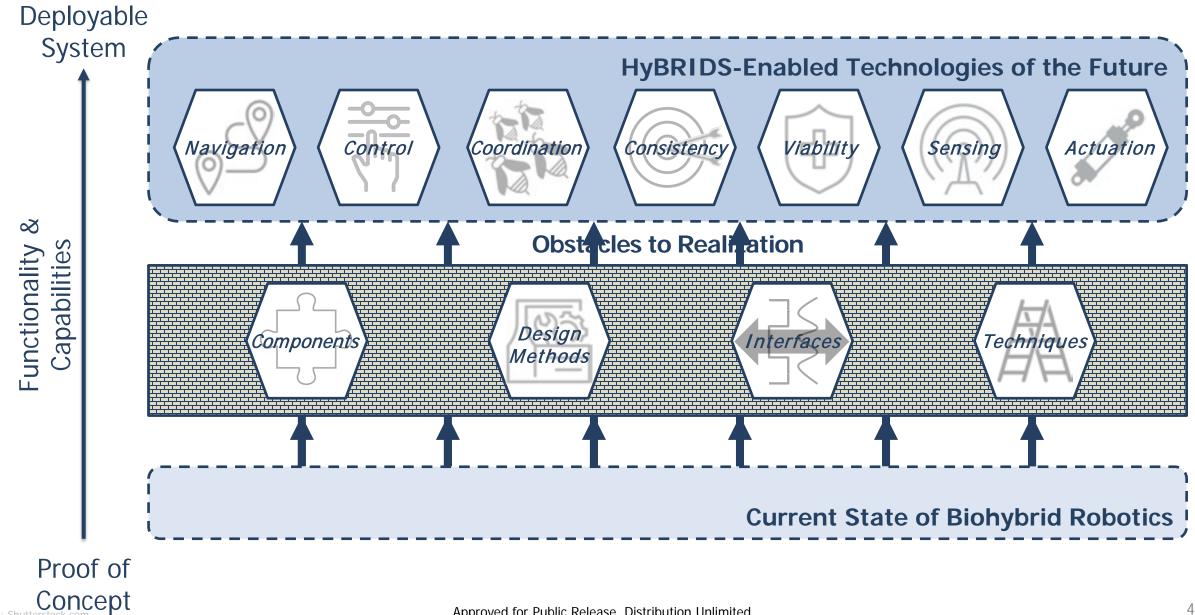






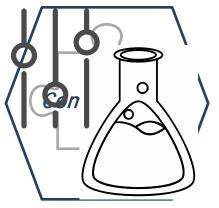
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## **Turning Proofs of Concept into Deployable Systems**





**ARC Question:** How can synthetic and biological components be integrated to enable biohybrid platforms that outperform traditional robotic systems?

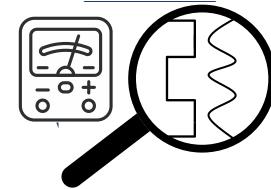


Modify Materials to Enhance Integration



Analyze and Predict Properties

and Performance



echnique.

Systematically Characterize Interfaces

Elicit Properties with Repeatable Strategies

### Potential areas of focus

- Relationship between system- and componentlevel performance
- Maintaining operational integrity

- Quantitatively measuring characteristics and performance over time
- Resilient interfaces that transmit information, • energy, load, and material



- Analytical framework contextualizing the proposed idea:
  - Identify addressed obstacle(s) and potential application and deployment environment
  - Quantify relevant performance of current systems in relevant application domain
  - Justify through clear quantitative calculations how, and to what extent, concept could exceed performance of existing alternatives
- Explain which regimes, and along which dimensions of performance, proposed biohybrid system could demonstrably outperform fully synthetic ones

#### Out of Scope

- Fully synthetic systems (including bioinspired and biomimetic systems)
- Incremental enhancements to existing functionalities or individual components
- Human subjects research or animal use

See Section II.B of DARPA-EA-25-02-02 for abstract instructions

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